runit and ignite:
a suckless init system?

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Motivation

Since mid-2012, there has been a strong drive by many Linux distributions towards replacing old *sysvinit* with newer systems such as *upstart* (Ubuntu), *openRC* (Gentoo) and *systemd* (everything else).

While these implement some long wished-for features, they also add lots of complexity, often in the wrong places.

When Arch Linux decided to move towards *systemd*, I had to pull the communication cord...

What *init(8)* must do:

- Be pid 1.
- Reap children (handle SIGCHLD).
- Run something to bring up the rest of the system.
- Don't crash. Ever.

  Everything else probably does not belong into pid 1.

What an *init system* should do:

- Configure the system according to some files or boot flags.

- Allow to start and stop services.

Service supervision

When we want a service to run, it should run.

When we want a service to stop, it should be stopped.

How can we know a service is running? *sysvinit* (and badly written *systemd* descriptions) use *pid files*, and check if the pid is still running, or kill it.

This is inherently racy. The pid can get invalidated and reassigned at any time.

Service supervision

The *only* way to reliably run a service is to be its parent process.
(You then get the pid from *fork(2)*.)

This also means *dæmonization* is a waste of time.

runsv(8)

runit provides *runsv(8)*, which starts and monitors a single service.

> *runsv* switches to the directory service and starts
> `./run`. If `./run` exits and `./finish` exists, *runsv*
> starts `./finish`. If `./finish` doesn't exist or
> `./finish` exits, *runsv* restarts `./run`.
>
> If `./run` or `./finish` exit immediately, *runsv* waits
> a second before starting `./finish` or restarting
> `./run`.

sv(8)

runit provides a tool *sv(8)* to talk to a running *runsv*:

- `sv status`
- `sv up`
- `sv down`
- `sv pause/cont/hup/alarm/interrupt/quit/1/2/term/kill`
- `sv exit`
- `sv restart`
- `sv check` (can be used to implement dependencies)

These tools communicate over a FIFO `./supervise/control` in the service directory.

runsvdir(8)

runsvdir(8) starts a *runsv(8)* process for each subdirectory, or symlink to a directory, in the services directory dir, up to a limit of 1000 subdirectories, and restarts a *runsv(8)* process if it terminates.

Putting it all together

We now have everything we need for service supervision.

You can use the mentioned parts on almost every Unix system already. (It runs on Linux, *BSD, MacOS X and Solaris.) I highly recommend it!

But we wanted to replace *init(1)*, too.

runit(8)

- *runit(8)* must be run as pid 1.
- *runit* runs /etc/runit/1 and waits for it to terminate.
- *runit* runs /etc/runit/2, which should not return until system shutdown.
- If *runit* is told to shutdown the system, or stage 2 returns, it terminates stage 2 if it is running, and runs /etc/runit/3.
- If stage 3 returns, *runit* checks if the file /etc/runit/reboot exists and has the execute by owner permission set. If so, the system is rebooted, it's halted otherwise.
- If *runit* receives a CONT signal and the file /etc/runit/stopit exists and has the execute by owner permission set, *runit* is told to shutdown the system.

The tools are there now.

But we don't have the /etc/runit/{1,2,3} scripts yet to actually do the stuff. (Nor do we have all the service directories.)

This is the task fulfilled by the *ignite* project.

ignite

ignite is a set of shell scripts to boot an Arch installation with *runit*.

It includes /etc/runit/{1,2,3} as well as service directories for many popular services (53 currently).

/etc/runit/{1,3} were written after a close reading of Arch *initscripts-2012.05.1*, back when these were simple bash scripts.

They support the rc.conf configuration file for system-wide configuration that Arch used to have.

These scripts are pretty straight forward:

```
% wc -l /etc/runit/?
  83 /etc/runit/1
  40 /etc/runit/2
  46 /etc/runit/3
 169 total
```

How to boot Arch Linux? · **/etc/runit/1**

- Mount /proc, /sys, /run, /dev, /dev/pts, /dev/shm
- Remount / read-only
- Enable Unicode for all Linux consoles, and load console fonts and fontmaps
- Load the console keymap
- Get the clock from the hardware clock
- Run *udev*
- Turn on local networking (interface *lo*)

- Set the hostname
- Deal with dmraid, btrfs, LVM, cryptsetup
- *fsck* if needed or requested
- Remount / read-write
- Mount other filesystems
- Enable swap
- Set the time zone
- Seed the random number generator
- Clear some files
- Save boot dmesg

What next? · **/etc/runit/2**

- Assemble list of services we want to run from `rc.conf`.

- Run /etc/rc.local, for one-time jobs (e.g. set some power saving options).

- Exec *runsvdir(8)*.

Shutting down Arch Linux? · **/etc/runit/3**

- Stop all services
- Run /etc/rc.local.shutdown
- Save the random number generator seed
- Quit *udev*
- Kill all processes still around
- Turn off swap
- Unmount everything but /
- Close all cryptdevices, LVM
- Remount / read-only
- Tell *runit* to halt or reboot

Sample services

```
#!/bin/sh
install -d -m 0755 -o root -g root /var/run/dovecot
exec dovecot -F
```

We include a *pause(2)* utility if there is nothing to supervise:

```
#!/bin/sh
/usr/sbin/alsactl restore
exec chpst -b alsa pause
```

Most services are easy to write.

ignite in practice

```
runit
  |-runsvdir -P /run/runit/runsvdir/current...
  |   |-runsv dovecot
  |   |   '-dovecot -F
  |   |       |-anvil
  |   |       |-imap
  |   |       '-log
  |   |-runsv postfix
  |   |   '-master -d
  |   |       |-pickup -l -t unix -d -u
  |   |       |-qmgr -l -t unix -d -u
  |   |       '-tlsmgr -l -t unix -d -u
  |   |-runsv sshd
  |   |   '-sshd -D
  |   |-runsv ntpd
```

```
|   |       '-ntpd -g -u ntp -n
|   |-runsv crond
|   |   '-crond -n
|   |       '-crond -n
|   |           '-(run-parts)
|   |-runsv wlan0-wpa
|   |   |-logger -t wpa_supplicant-
|   |   '-wpa_supplicant -i wlan0 -D nl80211,wext...
|   |-runsv wlan0
|   |   '-dhcpcd -qLB -t 0 wlan0
|   |-runsv eth0
|   |   '-dhcpcd -qLB -t 0 eth0
|   |-runsv syslog-ng
|   |   '-syslog-ng -F
|   '-runsv agetty-tty1
|       '-agetty -8 -s 38400 --noclear tty1 linux
'-udevd --daemon
```

ignite features: general

- Support for old-style `rc.conf` (snippet from my notebook):

```
TIMEZONE="Europe/Berlin"
MODULES=(acpi_cpufreq coretemp pcrypt snd-pcm-oss
  hdaps tp_smapi kvm-intel)
DAEMONS=(agetty-tty{1,2,3,4,5,6} syslog-ng smartd dkms
  hdapsd alsa !laptop-mode eth0 wlan0 wlan0-wpa crond
  ntpd acpid sshd postfix dovecot cpupower dbus mpd
  unbound batt-led)
```

- Services for networking: DHCP and static configurations
- Pretty straight forward to write service scripts for most dæmons
- *sysvinit* feelalikes for *halt(8)*, *reboot(8)*, *shutdown(8)*.

ignite features: robustness

- Interrupt support during boot: drop into a rescue shell in case boot fails
- Single-user mode support with read-only / (amazingly hard these days)
- Boot logging into *dmesg* kernel buffer

```
[   34.630993] :: mount -o remount,rw /
[   34.631160] EXT4-fs (dm-2): re-mounted. Opts: (null)
[   34.633807] :: mount -a -t "nosysfs,nonfs,nonfs4,nosmbfs,nocifs" -O no_netdev
[   34.635186] EXT4-fs (sdb1): mounting ext2 file system using the ext4 subsystem
```

ignite features: boot time

- Faster than *sysvinit*, since *runsvdir* starts all services in parallel.
- Slightly slower than *systemd* in practice:
    - need to wait for *udev* to settle completely
    - enabling UTF-8 on all 64 consoles takes some time in shell
    - *runsv* waits a second before it starts the service (could be patched out)
- In general, I don't think boot time is that important:
  It's fast enough.

ignite features: resource usage

- Small and mature code base (*runit* with all tools is about 5kLOC):

```
% wc -l runit.c sv.c runsv.c runsvdir.c
  346 runit.c
  387 sv.c
  607 runsv.c
  286 runsvdir.c
```

- Very lightweight, thanks to statically linked musl binaries (x86_64):

```
   text    data     bss     dec     hex filename
  12320     224     424   12968    32a8 /sbin/runit
  20044     224     888   21156    52a4 /sbin/runsv
  17460     280    8904   26644    6814 /sbin/sv
  32080    2156     672   34908    885c /sbin/init.sysv
 881017  106924    2497  990438   f1ce6 /usr/lib/.../systemd
```

- Very low overhead (measured on a Raspberry Pi):

```
 PID TIME  MAJFL  TRS   DRS   RSS %MEM COMMAND
   1 0:02     33  735  3980  2488  1.1 /sbin/init
  66 0:00      4  165  3294  1072  0.5 .../systemd-journald

 PID TIME  MAJFL  TRS   DRS   RSS %MEM COMMAND
   1 0:01      0   13   142    20  0.0 runit
 253 0:00      2   21   162    40  0.0 runsvdir
 267 0:00      0   21   142    32  0.0 runsv sshd
 269 0:00      1   21   142    32  0.0 runsv crond
 270 0:00      0   21   142    32  0.0 runsv eth0
 272 0:00      0   21   142    32  0.0 runsv agetty-tty1
```

- Runs *here* on about a dozen different machines (i686, x86_64, arm) for various tasks (notebooks, desktops, wall-hung tablet, print servers, NAS) with very similar setup.
- Generally stays out of your way.

Problems

- Some programs cannot not dæmonize (or make it tricky)
- Not all services are implemented (NFS)
- Some dependencies are hard/too general to describe
- Supervision of very early tasks
    - udev is not supervised (yet?)
    - want to run ntpdate early, but need network up already...
- Still using *syslog-ng*
    - works, but complicates proper logging of shutdown
    - the runit way is to use *svlogd(8)* (much work to adapt all services)
- Arch defaults converge to *systemd*, not always reasonable (increases setup cost)

Summary

runit provides a lightweight, flexible and high-quality init system.

ignite shows that common Linux distributions can adopt *runit* without too much effort.

I recommend using *runit* for a suckless Linux distribution.

How to get it

- *http://smarden.org/runit/*
- *http://github.com/chneukirchen/ignite*
- *#ignite on irc.freenode.net*
- *packer –S ignite-git* (read the manual first)

Questions?